

# **SPECIFICATION OF ROBOT**

**YF003NDE94**

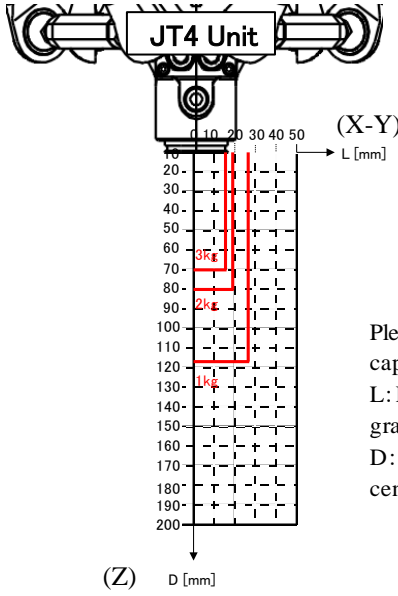
**2nd Edition : Nov.20.2013**

KAWASAKI HEAVY INDUSTRIES LTD.  
ROBOT DIV.

Doc, No:90101-2095DEB

# 1. Specification of Robot

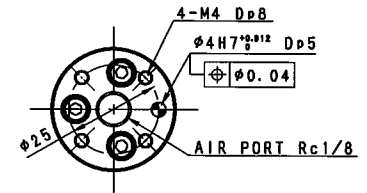
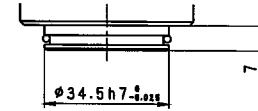
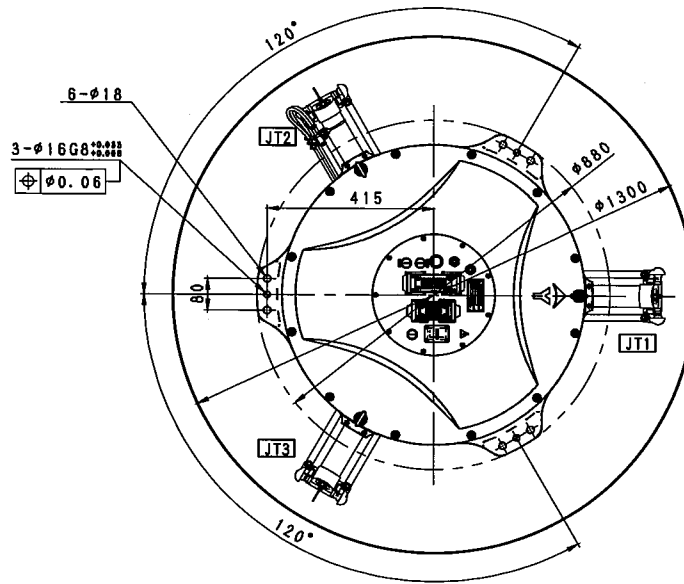
## [1] Robot Arm

1. Model	YF003N-A														
2. Type	Delta Parallel Robot														
3. Degree of freedom	4 axes														
4. Axis specification	Operating axis	Max. operating range	Max. speed												
	Arm rotation 1 (JT1)	+95° ~ -52.5°	1090.9°/s												
	Arm rotation 2 (JT2)	+95° ~ -52.5°	1090.9°/s												
	Arm rotation 3 (JT3)	+95° ~ -52.5°	1090.9°/s												
	Wrist twist (JT4)	+360° ~ -360°	1714.3°/s												
5. Palletizing Capacity (Maximum)	Approx. 175 pieces/min* (1kg weight, only robot arm) On the condition that robot moves 25 mm stroke in up-down direction and 305 mm stroke in right-left direction. * Including picking up and placing time 0.035 s each														
6. Position Repeatability	±0.10mm														
7. Angular Repeatability	±0.10°														
8. Max. payload	3kg														
9. Max. liner speed	10000mm/sec														
10. Load capacity of wrist	<div style="display: flex; align-items: center;">  <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>load [-]</th> <th>Max Torque [Nm]</th> <th>Max Moment [Nm]</th> </tr> </thead> <tbody> <tr> <td>1kg</td> <td>0.25</td> <td>1.15</td> </tr> <tr> <td>2kg</td> <td>0.37</td> <td>1.57</td> </tr> <tr> <td>3kg</td> <td>0.50</td> <td>2.06</td> </tr> </tbody> </table> </div> <p style="margin-left: 20px;">Please put the center of mass inside of the line of the each load capacity.  L: Distance in X-Y dimension from Z-axis to the mass center of gravity of the load.  D: Distance in Z dimension from X-Y dimension to the mass center of gravity of the load.</p>			load [-]	Max Torque [Nm]	Max Moment [Nm]	1kg	0.25	1.15	2kg	0.37	1.57	3kg	0.50	2.06
load [-]	Max Torque [Nm]	Max Moment [Nm]													
1kg	0.25	1.15													
2kg	0.37	1.57													
3kg	0.50	2.06													
11. Driving motor	Brushless AC Servomotor														
12. Working range	See attached drawing														
13. Mass	145 kg (without options)														
14. Color	Munsell 10GY9/1 equivalent														
15. Installation	Ceiling mounting														
16. Environment cond.	(Temperature) 0 ~ 45 °C, (Relative Humidity) 35 ~ 85 % (non-condensation)														
17. Degree of Protection	IP65 equivalent														
18. Built-in utilities	Pneumatic piping ( φ 10 x 1 line)														
19. Options	5 Axis (Brakeless)														
	IP67 equivalent														
20. Others	Consult Kawasaki about maintenance parts and spare parts.														

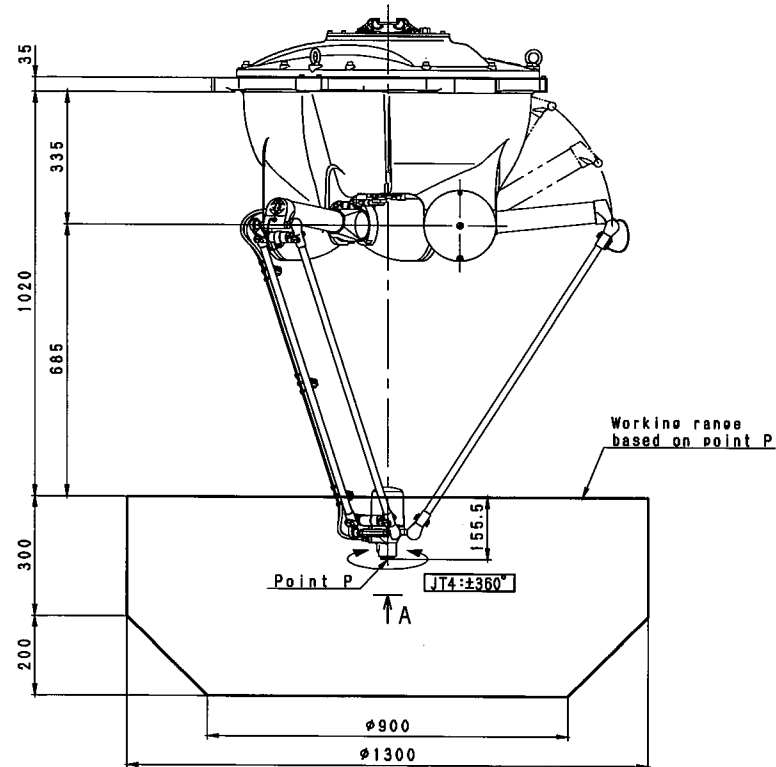
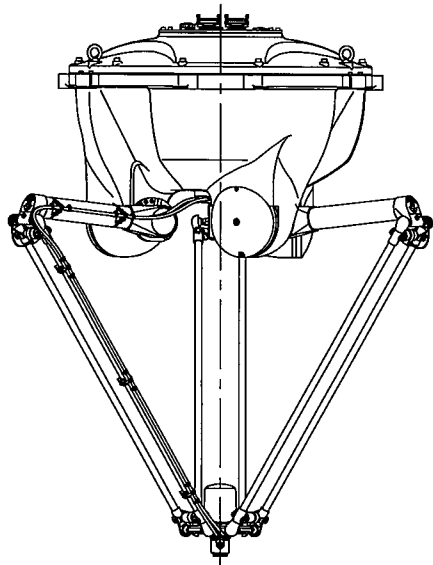
[2] Controller		
1. Model	E94	
2. Enclosure	Open structure / Direct cooling system † Note	
3. Dimensions	See attached drawing	
4. Number of controlled axes	Max.6 axes	
5. Servo control and drive system	Full Digital Servo System	
6. Type of control	Teach mode	Joint, Base, Tool, Fixed Tool (option) operation mode
	Repeat mode	PTP, CP control mode Joint, Linear, Circular (option) interpolation
7. Teaching method	Teaching or AS language programming	
8. Memory capacity	8 MB	
9. External operation signals	External Motor Power Off, External Hold, etc.	
10. General purpose signals	Input signals	32 channels (Includes dedicated signals)
	Output signals	32 channels (Includes dedicated signals)
11. Operation panel	Teach/Repeat SW, Emergency Stop SW, Control power lamp	
12. Cable length	Power/Signal cable	5 m
	Teach Pendant cable	5 m
13. Mass	See attached drawing	
14. Power requirement	AC200 V - AC230 V±10%, 50/60 Hz, 1 phases, Max 4 kVA	
15. Ground	Less than 100 Ω (robot dedicated ground) Leakage current: max. 100 mA	
16. Ambient temperature	0 - 45 °C	
17. Relative humidity	35 - 85 % (non-condensation)	
18. Color	Munsell: 10GY9/1 equivalent	
19. Teach Pendant	TFT color display (5.7 inch LCD) with touch panel Emergency Stop SW, Teach Lock SW and Enable SW	
20. Options		
General purpose signals	Input signals	64/96 channels
	Output signals	64/96 channels
I/O connector	D-SUB 37pin(male,female) with cover	
Operation panel	Motor Power ON, Cycle start, RUN/HOLD, Error reset, Error lamp	
Power/Signal cable	10m, 15m	
Teach Pendant cable	10m, 15m	
Enclosure	Enclosed structure / Indirect cooling system (Ambient temperature 0 - 40 °C )	
Auxiliary storage	USB memory	
Brake release	Brake release switch	
PC cable	1.5 m, 3 m	
Teach Pendant option	Connector for TP less	
Others	Field BUS, Software PLC, Analog input/output, Conveyor Synchronization, Vision and so on	
21. Others	Consult Kawasaki about maintenance parts and spare parts.	

† Note

Cooling of the electronic components in this open construction E9x controller is achieved by circulation of ambient air. The enclosure is designed to protect personnel from coming in contact with hazardous parts inside the controller. For environment where conductive dust like metal dust, non-conductive dust which becomes conductive due to condensation, or moisture exists, please select the option " Enclosed structure / Indirect cooling system ".



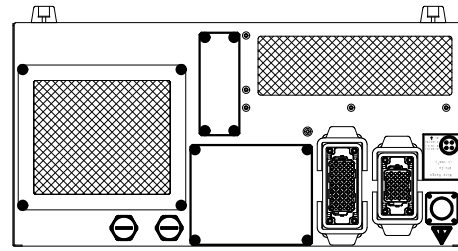
VIEW A



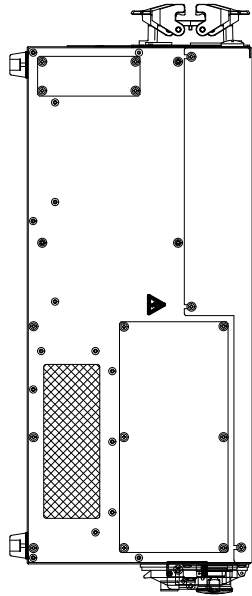
YF003N-A  
 WORKING RANGE

E 9 4   C O N T R O L L E R

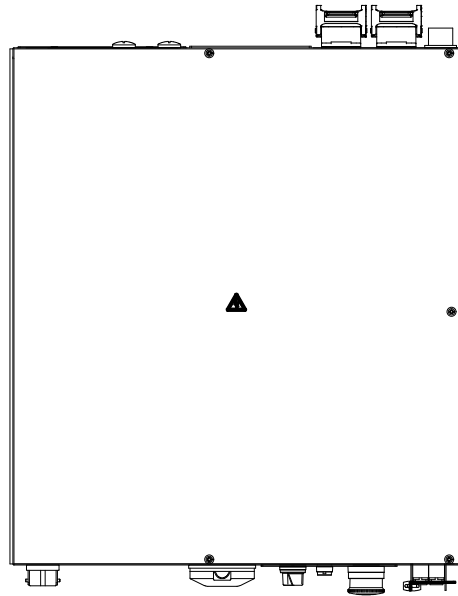
M A S S : 4 0 K g



R E A R   V I E W

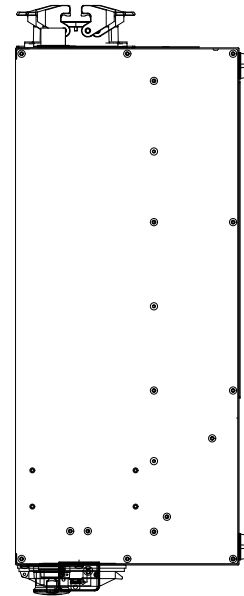


S I D E   V I E W

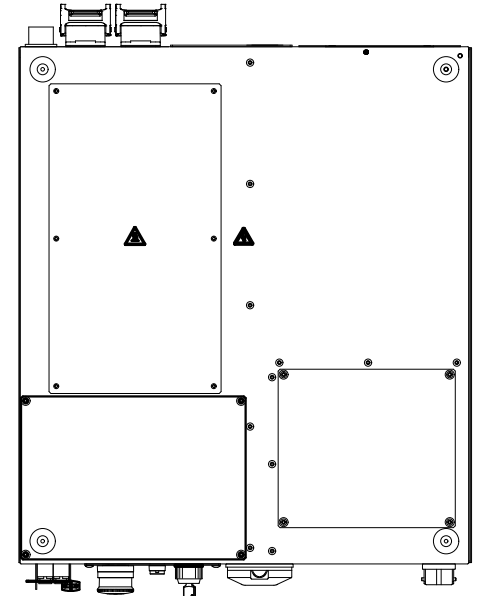


T O P   V I E W

( 5 0 )  
5 8 0  
( 3 4 )

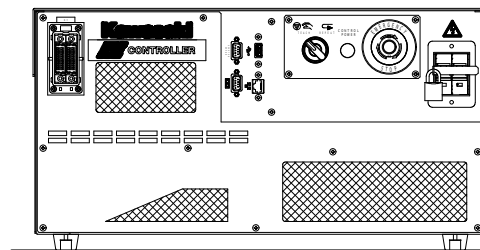
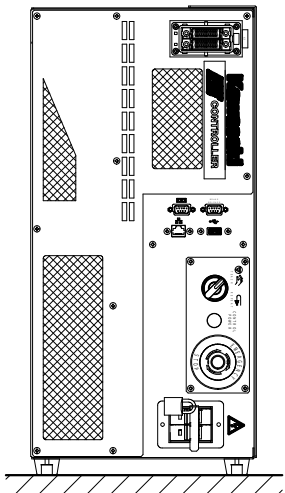


S I D E   V I E W



B O T T O M   V I E W

Vertical Mount  
縦置の場合



F R O N T   V I E W

2 5 0  
5 0 0  
1 8

